Docket No. R.304987

Preliminary Amdt.

**AMENDMENTS TO THE CLAIMS:** 

This listing of claims will replace all prior versions, and listings, of claims in the

application:

**Listing of Claims:** 

Claims 1-8. (Canceled)

9. (New) In a machine for filling and sealing two-part capsules, in particular hard gelatin

capsules, having a capsule delivery device, which has receptacles, each for one capsule, and

having at least one capsule expulsion station, which includes

a capsule expulsion device for axially expelling the capsules each out of their

respective receptacle;

guide flaps, individually controllable by means of an actuating device and pivotable

with respect to a pivot shaft, which are each assigned to one capsule receptacle and each have

two guideways, triggerable by means of the actuating device, for the respective associated

capsules, and

partitions, which separate the guideways of adjacent guide flaps from one another,

the improvement wherein the partitions are each an integrated component of a

respective guide flap.

10. (New) The machine in accordance with claim 9, wherein the guide flaps are supported

on a common pivot shaft.

Page 6 of 11

Docket No. R.304987

Preliminary Amdt.

11. (New) The machine in accordance with claim 9, wherein that the guide flaps cooperate

with two rows of capsule receptacles.

12. (New) The machine in accordance with claim 10, wherein that the guide flaps cooperate

with two rows of capsule receptacles.

13. (New) The machine in accordance with claim 9, wherein adjacent guide flaps are

separated from one another across a gap, which is preferably defined by a step in the bearing

region of at least one of the adjacent guide flaps.

14. (New) The machine in accordance with claim 10, wherein adjacent guide flaps are

separated from one another across a gap, which is preferably defined by a step in the bearing

region of at least one of the adjacent guide flaps.

15. (New) The machine in accordance with claim 11, wherein adjacent guide flaps are

separated from one another across a gap, which is preferably defined by a step in the bearing

region of at least one of the adjacent guide flaps.

16. (New) The machine in accordance with claim 9, further comprising means for subjecting

at least one of the guideways of each guide flap is subjected to suction.

Page 7 of 11

Docket No. R.304987

Preliminary Amdt.

17. (New) The machine in accordance with claim 9, wherein the expulsion device comprises

a plurality of tappets which are assigned one to each capsule receptacle.

18. (New) The machine in accordance with claim 10, wherein the expulsion device

comprises a plurality of tappets which are assigned one to each capsule receptacle.

19. (New) The machine in accordance with claim 11, wherein the expulsion device

comprises a plurality of tappets which are assigned one to each capsule receptacle.

20. (New) The machine in accordance with claim 13, wherein the expulsion device

comprises a plurality of tappets which are assigned one to each capsule receptacle.

21. (New) The machine in accordance with claim 16, wherein the expulsion device

comprises a plurality of tappets which are assigned one to each capsule receptacle.

22. (New) The machine in accordance with claim 9, wherein the guide flaps are each

triggerable by means of a respective pneumatic cylinder.

23. (New) The machine in accordance with claim 10, wherein the guide flaps are each

triggerable by means of a respective pneumatic cylinder.

Page 8 of 11

Docket No. R.304987 Preliminary Amdt.

24. (New) The machine in accordance with claim 11, wherein the guide flaps are each

triggerable by means of a respective pneumatic cylinder.

25. (New) The machine in accordance with claim 13, wherein the guide flaps are each

triggerable by means of a respective pneumatic cylinder.

26. (New) The machine in accordance with claim 16, wherein the guide flaps are each

triggerable by means of a respective pneumatic cylinder.

27. (New) The machine in accordance with claim 17, wherein the guide flaps are each

triggerable by means of a respective pneumatic cylinder.

28. (New) The machine in accordance with claim 9, wherein the actuating device for the

guide flaps cooperates with at least one inspection station for the capsules.